

MEC 654
Polytechnique-UPMC-Caltech
Year 2014-2015

Turbulence

chapter 17
eddy viscosity models

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17.1 the eddy viscosity concept (...)

- eddy viscosity : a first level approach for closing the Reynolds equations

case of the flow of a newtonian incompressible and homogeneous fluid without external force

- ✓ Navier-Stokes $\begin{cases} \text{div } \underline{u} = 0 \\ \frac{d \underline{u}}{dt} = \text{div } \underline{\underline{\sigma}} \end{cases}$
 - ✓ Cauchy stress tensor (see chapter 3) $\underline{\underline{\sigma}} = -\overbrace{p}^{\text{pressure}} \underline{1} + \overbrace{\underline{\underline{\tau}}}^{\text{viscous stress tensor}}$
 - ✓ newtonian constitutive law (see chapter 3) $\underline{\underline{\tau}} = \kappa \underline{\underline{\text{div}}} \underline{u} + 2\eta \left[\underline{\underline{d}} - \frac{1}{3} \underline{\underline{\text{div}}}(\underline{u}) \underline{1} \right]$
- $$\Rightarrow \underline{\underline{\sigma}} = -p \underline{1} + 2\eta \underline{\underline{d}}$$
- ✓ the Reynolds equation (see chapter 12)

$$\begin{cases} \rho \frac{D \langle \underline{u} \rangle}{Dt} = \text{div}(\langle \underline{\underline{\sigma}} \rangle - \rho \underline{\underline{R}}) \\ \langle \underline{\underline{\sigma}} \rangle = -\langle p \rangle \underline{1} + 2\eta \langle \underline{\underline{d}} \rangle \\ \underline{\underline{R}} = \langle \underline{u}' \otimes \underline{u}' \rangle \quad \text{- Reynolds stress tensor} \end{cases}$$

17.1 the eddy viscosity concept (...)

- ✓ the Reynolds equation (see chapter 12)

$$\begin{cases} \frac{D \langle \underline{u} \rangle}{Dt} = \text{div} \left(\frac{1}{\rho} \langle \underline{\underline{\sigma}} \rangle - \underline{\underline{R}} \right) \\ \langle \underline{\underline{\sigma}} \rangle = -\langle p \rangle \underline{1} + 2\eta \langle \underline{\underline{d}} \rangle \\ \underline{\underline{R}} = \langle \underline{u}' \otimes \underline{u}' \rangle \quad \text{- Reynolds stress tensor} \end{cases}$$

- Boussinesq's eddy viscosity relationship

$$-\rho \underline{\underline{R}} \leftrightarrow \langle \underline{\underline{\sigma}} \rangle \quad \Rightarrow \quad \underline{\underline{R}} = -\alpha \underline{1} + \beta \langle \underline{\underline{d}} \rangle$$

- property

$$\text{trace} \{ \underline{\underline{R}} \} = \langle u_i^2 \rangle = \langle u_1^2 \rangle + \langle u_2^2 \rangle + \langle u_3^2 \rangle = 2k = 3\alpha - \beta \text{div} \langle \underline{u} \rangle$$

$$\Rightarrow \alpha = \frac{2}{3}k \quad \Rightarrow \quad \underline{\underline{R}} = -\frac{2}{3}k \underline{1} + \beta \langle \underline{\underline{d}} \rangle \quad \Rightarrow \quad \frac{2}{3}k = \text{"turbulent pressure"}$$

- analogy

$$\underline{\underline{R}} = -\frac{2}{3}k \underline{1} + \beta \langle \underline{\underline{d}} \rangle \quad \Rightarrow \quad \underline{\underline{R}} = \frac{2}{3}k \underline{1} - 2\nu_\epsilon \langle \underline{\underline{d}} \rangle$$

$$\begin{matrix} \uparrow \\ \beta = 2\nu_\epsilon \\ \nu_\epsilon = \text{dynamic eddy viscosity} \end{matrix}$$

17.1 the eddy viscosity concept (...)

$$\begin{cases}
 \frac{D\langle \underline{u} \rangle}{Dt} = \text{div} \left(\frac{\langle \underline{\sigma} \rangle}{\rho} - \underline{R} \right) \\
 \langle \underline{\sigma} \rangle = -\langle p \rangle \underline{1} + 2\eta \langle \underline{d} \rangle \\
 -\underline{R} = \langle \underline{u}' \otimes \underline{u}' \rangle \quad \text{- Reynolds stress tensor} \\
 -\underline{R} + \frac{2}{3} k \underline{1} = 2 \nu_\epsilon \langle \underline{d} \rangle \quad \text{- Boussinesq's "eddy viscosity" closure relationship}
 \end{cases}$$

$$\Rightarrow \frac{D\langle \underline{u} \rangle}{Dt} = \text{div} \left[-\left(\frac{1}{\rho} \langle p \rangle + \frac{2}{3} k \right) \underline{1} + 2(\nu + \nu_\epsilon) \langle \underline{d} \rangle \right]$$

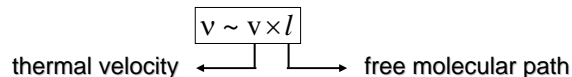
$$\Rightarrow \frac{D\langle \underline{u} \rangle}{Dt} = -\frac{1}{\rho} \text{grad} \langle \tilde{p} \rangle + \text{div} \left[2(\nu + \nu_\epsilon) \langle \underline{d} \rangle \right]$$

$$\langle \tilde{p} \rangle = \langle p \rangle + \frac{2}{3} \rho k \rightarrow \text{turbulent pressure}$$

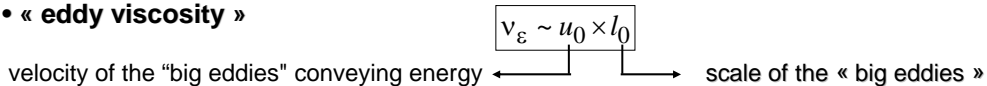
• a closed equation $\begin{cases}
 \| \underline{u} \| \sim U \\
 p \sim \rho U^2
 \end{cases}
 \Rightarrow \frac{\langle \tilde{p} \rangle}{\langle p \rangle} = 1 + \frac{2}{3} \frac{k}{U^2} \approx 1 \quad \text{if } \frac{k}{U^2} \ll 1 \text{ (turbulent rate)}$

17.1 the eddy viscosity concept (...)

• physical viscosity



• « eddy viscosity »



• zero-equation closure model

\Rightarrow expressing u_0, l_0 as functions of the mean field : the mixing length model

• one - equation closure model

\Rightarrow one can write down an equation for the « eddy viscosity » ν_ϵ

• two-equation closure model

\Rightarrow an equation for u_0 , another for l_0

✓ a popular approach is the $k - \epsilon$ model

$$\begin{cases}
 u_0 \sim \sqrt{k} \\
 l_0 \sim \frac{u_0^3}{\epsilon} \sim \frac{k^{3/2}}{\epsilon}
 \end{cases}
 \Rightarrow \nu_\epsilon = \text{const.} \times \frac{k^2}{\epsilon} \Leftarrow \begin{cases}
 \text{need of a } k \text{ - equation} \\
 \text{need of an } \epsilon \text{ - equation}
 \end{cases}$$

17.2 criticism

- **Boussinesq**

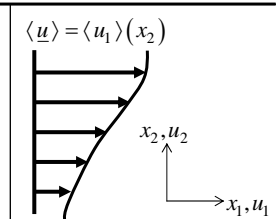
$$\langle \underline{u}' \otimes \underline{u}' \rangle - \frac{2}{3} k \underline{1} = -2\nu_\varepsilon \langle \underline{d} \rangle$$

- ✓ through the Boussinesq's « eddy viscosity » concept, turbulence is treated as a new **viscosity**, that is as a new **physical** property of the **fluid**. this is not justified because turbulence is a **dynamical** property of the flow
 - ✓ through this relationship, the turbulence has **no autonomy** : it follows rigidly and instantaneously the mean flow distortions
 - ✓ introducing $\begin{cases} \tau_d = |\langle \underline{d} \rangle|^{-1} & \text{- mean distortion time scale} \\ \tau_\varepsilon = k/\varepsilon & \text{- turbulence turnover time scale} \end{cases}$
- the hypothesis is **admissible** when turbulence is "in equilibrium", namely when $\tau_d \gg \tau_\varepsilon$ that is in flows whose average properties only change little along the mean streamlines, as in **equilibrium boundary layers**, in **mixing layers**, in **jets**...
- ✓ this is **unsatisfactory** when $\tau_d \sim \tau_\varepsilon$ as for instance in **separated flows**, in **strongly curved flows** or in **shocked flows**...

17.3 application : quasi-parallel shear flows

- **hypotheses** H1 - statistically steady turbulence

H2 - quasi-parallel flow : $\frac{\partial}{\partial x_1} \sim \frac{\partial}{\partial x_3} \ll \frac{\partial}{\partial x_2}$



- **Boussinesq**

$$-\langle \underline{u}' \otimes \underline{u}' \rangle + \frac{2}{3} k \underline{1} = 2\nu_\varepsilon \langle \underline{d} \rangle$$

$$\begin{aligned} \Rightarrow \langle \underline{d} \rangle &= \frac{1}{2} (\nabla \langle \underline{u} \rangle + {}^t \nabla \langle \underline{u} \rangle) \approx \frac{1}{2} \frac{\partial \langle u_1 \rangle}{\partial x_2} (e_1 \otimes e_2 + e_2 \otimes e_1) \\ \Rightarrow \langle \underline{d} \rangle_{ij} &\approx \frac{1}{2} \frac{\partial \langle u_1 \rangle}{\partial x_2} (\delta_{i1} \delta_{j2} + \delta_{i2} \delta_{j1}) \\ \Rightarrow -\langle \underline{u}' \otimes \underline{u}' \rangle + \frac{2}{3} k \underline{1} &= \nu_\varepsilon \frac{\partial \langle u_1 \rangle}{\partial x_2} (e_1 \otimes e_2 + e_2 \otimes e_1) \\ \Rightarrow -\langle u'_i u'_j \rangle + \frac{2}{3} k \delta_{ij} &= \nu_\varepsilon \frac{\partial \langle u_1 \rangle}{\partial x_2} (\delta_{i1} \delta_{j2} + \delta_{i2} \delta_{j1}) \\ \Rightarrow \begin{cases} \langle u_1'^2 \rangle = \langle u_2'^2 \rangle = \langle u_3'^2 \rangle \approx \frac{2}{3} k \\ -\langle u_1' u_2' \rangle \approx \nu_\varepsilon \frac{\partial \langle u_1 \rangle}{\partial x_2} \\ \langle u_1' u_3' \rangle = \langle u_2' u_3' \rangle \approx 0 \end{cases} \end{aligned}$$

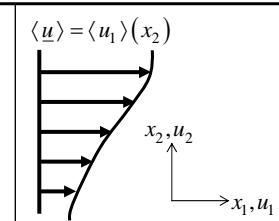
17.3 application : quasi-parallel shear flows (...)

• **hypotheses** H1 - statistically steady turbulence

H2 - quasi-parallel flow : $\frac{\partial}{\partial x_1} \sim \frac{\partial}{\partial x_3} \ll \frac{\partial}{\partial x_2}$

• **Reynolds equation**

$$\begin{cases} \text{div } \underline{u} = 0 \\ D\langle \underline{u} \rangle / Dt = -\text{grad } \langle \tilde{p} \rangle / \rho + \text{div} [2\nu \langle \underline{d} \rangle - \langle \underline{u}' \otimes \underline{u}' \rangle] \\ \langle \tilde{p} \rangle = \langle p \rangle + 2\rho k / 3 \end{cases}$$



✓ following Prandtl's boundary layer analysis and introducing the previous Boussinesq's relationships, one can show that this reduces to (see annex) :

$$\begin{cases} \langle u_1 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_1} + \langle u_2 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_2} = (v + v_\varepsilon) \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2} \\ \langle p \rangle + \frac{4}{3} \rho k \approx \text{const.} \end{cases}$$

note - turbulence contributes to a second order variation of the mean pressure, we neglect usually because the turbulence rate is small (see above, §16.1)

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annex - Reynolds equation for a quasi parallel shear flow

• the different terms of the Reynolds system of equations given above read :

$$\checkmark \quad \frac{D\langle \underline{u} \rangle}{Dt} = \frac{\partial \langle \underline{u} \rangle}{\partial t} + \langle u_1 \rangle \frac{\partial \langle \underline{u} \rangle}{\partial x_1} + \langle u_2 \rangle \frac{\partial \langle \underline{u} \rangle}{\partial x_2} + \langle u_3 \rangle \frac{\partial \langle \underline{u} \rangle}{\partial x_3}$$

$$\checkmark \quad \text{grad } \langle \tilde{p} \rangle = \text{grad} \left[\langle p \rangle + \frac{2}{3} \rho k \right] \approx \frac{\partial}{\partial x_2} \left[\langle p \rangle + \frac{2}{3} \rho k \right] \underline{e}_2$$

$$\checkmark \quad \langle \underline{d} \rangle = \frac{1}{2} (\nabla \langle \underline{u} \rangle + {}^t \nabla \langle \underline{u} \rangle) \approx \frac{1}{2} \frac{\partial \langle u_1 \rangle}{\partial x_2} (\underline{e}_1 \otimes \underline{e}_2 + \underline{e}_2 \otimes \underline{e}_1) \quad \Rightarrow \quad \text{div } \langle \underline{d} \rangle \approx \frac{1}{2} \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2} \underline{e}_1 + \frac{1}{2} \frac{\partial}{\partial x_1} \frac{\partial \langle u_1 \rangle}{\partial x_2} \underline{e}_2$$

$$\checkmark \quad \langle \underline{u}' \otimes \underline{u}' \rangle - \frac{2}{3} k \underline{1} = -v_\varepsilon \frac{\partial \langle u_1 \rangle}{\partial x_2} (\underline{e}_1 \otimes \underline{e}_2 + \underline{e}_2 \otimes \underline{e}_1) \quad \Rightarrow \quad \text{div } \langle \underline{u}' \otimes \underline{u}' \rangle \approx \frac{2}{3} \frac{\partial k}{\partial x_2} \underline{e}_2 - v_\varepsilon \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2} \underline{e}_1$$

$$\uparrow \\ \text{div} (k \underline{1}) = \text{grad } k$$

$$\Rightarrow \begin{cases} \frac{\partial \langle u_1 \rangle}{\partial x_1} + \frac{\partial \langle u_2 \rangle}{\partial x_2} = 0 \\ \langle u_1 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_1} + \langle u_2 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_2} = (v + v_\varepsilon) \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2} \\ \langle u_1 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_1} + \langle u_2 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_2} = -\frac{\partial}{\partial x_2} \left[\langle p \rangle + \frac{4}{3} \rho k \right] \\ \langle u_1 \rangle \frac{\partial \langle u_3 \rangle}{\partial x_1} + \langle u_2 \rangle \frac{\partial \langle u_3 \rangle}{\partial x_2} = 0 \end{cases}$$

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annex - Reynolds equation for a quasi parallel shear flow (...)

• orders of magnitude analysis

✓ putting

$$\begin{cases} \partial/\partial x_1 = O(L^{-1}) \\ \partial/\partial x_2 = O(\delta^{-1} \gg L^{-1}) \\ \langle u_1 \rangle = O(U) \\ \langle u_2 \rangle = O(V) \\ \langle p \rangle = O(\rho U^2) \end{cases}$$

✓ the continuity equation imposes $\frac{\partial \langle u_1 \rangle}{\partial x_1} + \frac{\partial \langle u_2 \rangle}{\partial x_2} = 0 \Rightarrow \frac{U}{L} \sim \frac{V}{\delta} \Rightarrow \frac{V}{U} \sim \frac{\delta}{L} \ll 1$

✓ orders of magnitude in the momentum equation then are :

$$\Rightarrow \begin{cases} \underbrace{\langle u_1 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_1}}_{O(U^2/L)} + \underbrace{\langle u_2 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_2}}_{O(UV/\delta=U^2/L)} = \underbrace{(v + v_\varepsilon) \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2}}_{O(\max\{v, v_\varepsilon\} U/\delta^2)} \\ \underbrace{\langle u_1 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_1}}_{O(UV/L=U^2/L \times \delta/L)} + \underbrace{\langle u_2 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_2}}_{O(V^2/\delta=U^2/L \times \delta/L)} = - \underbrace{\frac{\partial}{\partial x_2} \left[\frac{1}{\rho} \langle p \rangle + \frac{4}{3} k \right]}_{O(U^2/\delta=U^2/L \times L/\delta)} \end{cases}$$

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annex - Reynolds equation for a quasi parallel shear flow (...)

$$\Rightarrow \begin{cases} \underbrace{\langle u_1 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_1}}_{O(1)} + \underbrace{\langle u_2 \rangle \frac{\partial \langle u_1 \rangle}{\partial x_2}}_{O(1)} = \underbrace{(v + v_\varepsilon) \frac{\partial^2 \langle u_1 \rangle}{\partial x_2^2}}_{O\left(\frac{\max\{v, v_\varepsilon\}}{UL} \times \left(\frac{\delta}{L}\right)^2\right)} \\ \underbrace{\langle u_1 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_1}}_{O(1)} + \underbrace{\langle u_2 \rangle \frac{\partial \langle u_2 \rangle}{\partial x_2}}_{O(1)} = - \underbrace{\frac{\partial}{\partial x_2} \left[\frac{1}{\rho} \langle p \rangle + \frac{4}{3} k \right]}_{O((\delta/L)^{-2})} \end{cases}$$

✓ putting $Re = \frac{UL}{\max\{v, v_\varepsilon\}} \gg 1$, a viscous and/or turbulent flow regime requires :

$$Re^{-1} \left(\frac{\delta}{L}\right)^2 = 1 \Rightarrow \frac{\delta}{L} \sim \sqrt{Re}$$

✓ the u_2 - equation then reads :

$$\langle p \rangle + \frac{4}{3} \rho k \approx const.$$

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17.4 a displaced particle argument

• quasi parallel shear flow

✓ Boussinesq's relationship reads $\langle u'v' \rangle \approx -\nu_\epsilon \frac{\partial \langle u \rangle}{\partial y}$

• eddy viscosity $\nu_\epsilon \sim \nu l$

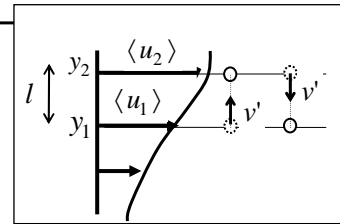
• a displaced particle argument

✓ let a fluid particle being displaced in a shear flow of rate $\frac{d\langle u \rangle}{dy} \approx \frac{\langle u_2 \rangle - \langle u_1 \rangle}{l}$

✓ supposing the horizontal momentum of the particle is conserved during the process :

> if $v' > 0$ the fluctuation u' at y_2 is : $u' = \langle u_1 \rangle - \langle u_2 \rangle = -l \frac{\partial \langle u \rangle}{\partial y}$
 > if $v' < 0$ the fluctuation u' at y_1 is : $u' = \langle u_2 \rangle - \langle u_1 \rangle = l \frac{\partial \langle u \rangle}{\partial y}$

$\left. \begin{array}{l} \text{ } \\ \text{ } \end{array} \right\} \Rightarrow \langle u'v' \rangle = -\frac{(|v|l)}{\nu_\epsilon (>0)} \frac{\partial \langle u \rangle}{\partial y}$



17.4 a displaced particle argument

• physical viscosity versus eddy viscosity

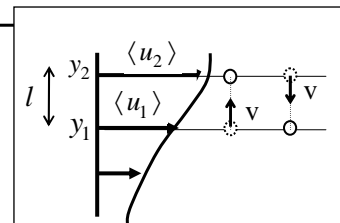
$$\langle u'v' \rangle = -\frac{(|v|l)}{\nu_\epsilon (>0)} \frac{\partial \langle u \rangle}{\partial y}$$

✓ physical viscosity $\left\{ \begin{array}{l} \text{thermal velocity } \nu \sim 300 \text{ m.s}^{-1} \\ \text{free molecular path } l \sim 10^{-7} \text{ m (gaz)} \end{array} \right\} \Rightarrow \nu \sim \nu \times l \sim 10^{-5} - 10^{-4} \text{ m}^2 \cdot \text{s}^{-1}$

✓ « eddy viscosity » $\left\{ \begin{array}{l} \text{« big eddies » velocity } u_0 \\ \text{« big eddies » scale } l_0 \end{array} \right\} \Rightarrow \nu_\epsilon \sim u_0 \times l_0 \quad \text{such as } Re_\epsilon = \frac{u_0 \times l_0}{\nu_\epsilon} \sim 1$

✓ mixing layer $\left\{ \begin{array}{l} u_0 \approx 0.1 \Delta U \\ l_0 \approx \delta(x) \end{array} \right\} \Rightarrow Re_\epsilon = \frac{\Delta U \times \delta(x)}{\nu} \frac{\nu}{\nu_\epsilon} = Re \frac{\nu}{\nu_\epsilon} \sim 1 \Rightarrow \nu_\epsilon \sim Re \times \nu$

✓ boundary layer $\left\{ \begin{array}{l} u_0 \approx u_\tau \\ l_0 \approx y \end{array} \right\} \Rightarrow Re_\epsilon = \frac{u_\tau \times y}{\nu} \frac{\nu}{\nu_\epsilon} = y^+ \frac{\nu}{\nu_\epsilon} \sim 1 \Rightarrow \nu_\epsilon \sim y^+ \times \nu$



17.5 a zéro equation model : the mixing length model (*)

- quasi parallel shear flow

$$\langle u' v' \rangle = - \underbrace{(|v| l)}_{v_\varepsilon (>0)} \frac{\partial \langle u \rangle}{\partial y}$$

⇒ the two scales v and l must be expressed directly as a function of the mean field

- the velocity scale v

✓ in a shear flow $|u'| \sim |\langle u_2 \rangle - \langle u_1 \rangle| = l \frac{\partial \langle u \rangle}{\partial y} \Rightarrow \langle u'^2 \rangle \sim l^2 \left(\frac{\partial \langle u \rangle}{\partial y} \right)^2$

✓ suppose now that $\langle u'^2 \rangle \approx \langle v'^2 \rangle$ (isotropy) : $v \sim \sqrt{\langle v'^2 \rangle} \sim \sqrt{\langle u'^2 \rangle} \sim l \left| \frac{\partial \langle u \rangle}{\partial y} \right|$

$$\Rightarrow \langle u' v' \rangle = - (|v| l) \frac{\partial \langle u \rangle}{\partial y} = - l^2 \left| \frac{\partial \langle u \rangle}{\partial y} \right| \frac{\partial \langle u \rangle}{\partial y} \Rightarrow v_\varepsilon = l^2 \left| \frac{\partial \langle u \rangle}{\partial y} \right|$$

- the “mixing length” l

✓ boundary layers : $l = \kappa y$, $\kappa = 0,4$ Von-Karman (1930)

✓ mixing layers : $l \sim (\Delta U / \bar{U}) x$

(*) Kolmogorov (1942), Prandtl (1945)

16.5 a zéro equation model : the mixing length model (...)

- quasi parallel shear flow

$$\langle u' v' \rangle = -v_\varepsilon \frac{\partial \langle u \rangle}{\partial y}$$

$$v_\varepsilon = l^2 \left| \frac{\partial \langle u \rangle}{\partial y} \right|$$

- generalisation

$$\langle \underline{u}' \otimes \underline{u}' \rangle = -v_\varepsilon \underline{d}$$

$$v_\varepsilon = v_\varepsilon(l, \nabla \underline{u})$$

Smagorinsky (1963)

$$v_\varepsilon = l^2 \sqrt{\langle \underline{d} \rangle : \langle \underline{d} \rangle}$$

$$\langle \underline{d} \rangle : \langle \underline{d} \rangle = 2 \left(\frac{\partial u_i}{\partial x_j} \right)^2 + 2 \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i}$$

see annex

Baldwin & Lomax (1978)

$$v_\varepsilon = l^2 \sqrt{\langle \underline{\Omega} \rangle : \langle \underline{\Omega} \rangle}$$

$$\langle \underline{\Omega} \rangle : \langle \underline{\Omega} \rangle = 2 \left(\frac{\partial u_i}{\partial x_j} \right)^2 - 2 \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i}$$

- ... and many other formulations, all being empirical

annex – Smagorinsky versus Baldwin-Lomax

$$\begin{aligned}
 \langle \underline{d} \rangle : \langle \underline{d} \rangle &= \frac{1}{4} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \left(\frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k} \right) (e_i \otimes e_j) : (e_l \otimes e_k) \\
 &= \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \left(\frac{\partial u_k}{\partial x_l} + \frac{\partial u_l}{\partial x_k} \right) \delta_{jl} \delta_{ik} = \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \\
 &= \left(\frac{\partial u_i}{\partial x_j} \right)^2 + \left(\frac{\partial u_j}{\partial x_i} \right)^2 + 2 \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i} = 2 \left(\frac{\partial u_i}{\partial x_j} \right)^2 + 2 \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i} \\
 \langle \underline{\Omega} \rangle : \langle \underline{\Omega} \rangle &= \frac{1}{4} \left(\frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right) \left(\frac{\partial u_k}{\partial x_l} - \frac{\partial u_l}{\partial x_k} \right) (e_i \otimes e_j) : (e_l \otimes e_k) \\
 &= \dots = 2 \left(\frac{\partial u_i}{\partial x_j} \right)^2 - 2 \frac{\partial u_i}{\partial x_j} \frac{\partial u_j}{\partial x_i}
 \end{aligned}$$

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17.6 a one-equation model : the Spalart-Allmaras model (*)

- a transport equation for the eddy viscosity

$$\frac{D v_\varepsilon}{Dt} = \underbrace{S_{v_\varepsilon}}_{\text{source of } v_\varepsilon} + \underbrace{\text{div} [\chi_\varepsilon \text{grad} (v_\varepsilon)]}_{\text{flux of } v_\varepsilon}$$

✓ source term $S_{v_\varepsilon} = f (v_\varepsilon, \text{grad} (v_\varepsilon), \Omega, l_{\min})$

where $\begin{cases} \Omega = \text{rotation rate} \\ l_{\min} = \text{minimum distance from the wall} \end{cases}$

✓ flux term $\begin{cases} \chi_\varepsilon = v_\varepsilon / \sigma_\varepsilon = \text{diffusivity of } v_\varepsilon \\ \sigma_\varepsilon = \text{turbulent Prandtl number} \end{cases}$

⇒ a "UFO", 100% empirical...that **works remarkably well** for the modeling of wall flows for which it has been conceived

(*) Spalart & Allmaras (1994)

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17.7 two - equation models : the $k - \varepsilon$ model (...)

- a transport equation for each of the two variables v and l of $v_\varepsilon \sim |v|l$

✓ velocity : $v \sim \sqrt{k}$

✓ lengthscale : using $\varepsilon = \frac{v^3}{l}$ leads to $l = \frac{v^3}{\varepsilon} \sim \frac{k^{3/2}}{\varepsilon}$ (*)

⇒ eddy viscosity : $v_\varepsilon \sim \frac{k^2}{\varepsilon} = C_\eta \frac{k^2}{\varepsilon}$ ⇒ need for a k - equation and for a ε - equation

- at first, let's check the validity of $v_\varepsilon = C_\eta \frac{k^2}{\varepsilon}$

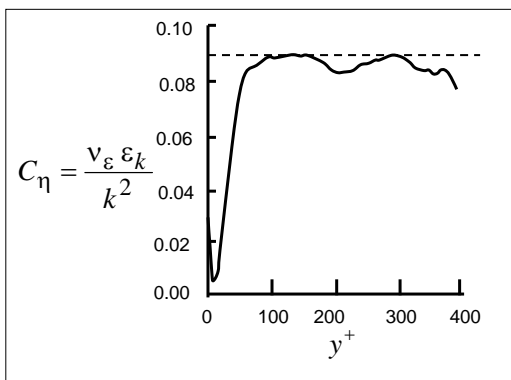
✓ let's consider quasi-parallel shear flows ⇒ next slide

(*) many contributors. Jones & Lauder (1972) for the foundations

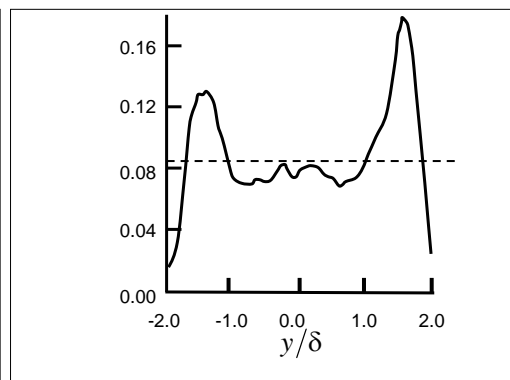
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17.7 two - equation models : the $k - \varepsilon$ model (...)

channel flow : DNS Re=13 750 (*)



temporal mixing layer : DNS (**)



⇒ correct in regions where turbulence is in equilibrium (logarithmic region, mixing layer center region)

⇒ in the standard $k - \varepsilon$ model: $C_\eta \approx 0.09$

(*) Rogers & Moser (1994) ; (**) Kim et al. (1987)

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17.7 two - equation models : the $k - \varepsilon$ model (...)

• **k - equation** $\frac{Dk}{Dt} = P + \text{div}(\phi_k) - \varepsilon_k$ $\left\{ \begin{array}{l} P \approx -\langle \underline{u}' \otimes \underline{u}' \rangle : \nabla \underline{u} = v_\varepsilon \nabla \langle \underline{u}' \rangle : \langle \nabla \underline{u}' \rangle \\ \phi_k = -\frac{1}{\rho} \langle p' \underline{u}' \rangle - \frac{1}{2} \langle \underline{u}'^2 \underline{u}' \rangle + v \underline{\text{grad}} k \\ \varepsilon_k = \varepsilon_{1k} = 2v \langle |\nabla \underline{u}'|^2 \rangle \end{array} \right.$

• **ε - equation** ($\varepsilon = \varepsilon_k$) : far too complex !

\Rightarrow one « mimics » the k -equation (**): $\frac{D\varepsilon}{Dt} = \underbrace{P_\varepsilon}_{\text{production}} + \text{div}(\underbrace{\phi_\varepsilon}_{\text{flux}}) - \underbrace{\varepsilon_\varepsilon}_{\text{destruction}}$

\Rightarrow **$k - \varepsilon$ modelling** $\left\{ \begin{array}{l} \langle \underline{u}' \otimes \underline{u}' \rangle = -v_\varepsilon \underline{d} \\ v_\varepsilon \sim \frac{k^2}{\varepsilon} = C_\mu \frac{k^2}{\varepsilon} \\ P = -\langle \underline{u}' \otimes \underline{u}' \rangle : \nabla \underline{u} = v_\varepsilon \underline{d} : \langle \nabla \underline{u}' \rangle \quad \text{- production} \\ \frac{Dk}{Dt} = P + \text{div}(\phi_k) - \varepsilon \\ \frac{D\varepsilon}{Dt} = \underbrace{P_\varepsilon}_{\text{production}} + \text{div}(\underbrace{\phi_\varepsilon}_{\text{flux}}) - \underbrace{\varepsilon_\varepsilon}_{\text{destruction}} \end{array} \right. \leftarrow \text{framed terms must be closed}$

17.7 two - equation models : the $k - \varepsilon$ model (...)

• **$k - \varepsilon$ modelling (...)** $\left. \begin{array}{l} \frac{Dk}{Dt} = P + \text{div}(\phi_k) - \varepsilon \\ \frac{D\varepsilon}{Dt} = \underbrace{P_\varepsilon}_{\text{production}} + \text{div}(\underbrace{\phi_\varepsilon}_{\text{flux}}) - \underbrace{\varepsilon_\varepsilon}_{\text{destruction}} \end{array} \right\} \leftarrow \text{framed terms must be closed}$

• **fluxes : first gradient formulation**

$\left\{ \begin{array}{l} \phi_a = \text{div}(\chi_\varepsilon \underline{\text{grad}} a) \\ \chi_\varepsilon = v_\varepsilon / \sigma_\varepsilon \quad \text{- diffusivity} \\ \sigma_\varepsilon \quad \text{- turbulent Prandtl number} \end{array} \right.$

• **dissipation rate : production - destruction**

$\left\{ \begin{array}{l} P_\varepsilon = C_{\varepsilon 1} \left(\frac{\varepsilon}{k} \right) P \quad \text{- production} \\ \varepsilon_\varepsilon = C_{\varepsilon 2} \left(\frac{\varepsilon}{k} \right) \varepsilon \quad \text{- destruction} \end{array} \right.$

✓ characteristic time scale $\tau = k/\varepsilon$

the $k - \varepsilon$ model

$\left\{ \begin{array}{l} \langle \underline{u}' \otimes \underline{u}' \rangle = -v_\varepsilon \underline{d} \\ v_\varepsilon = C_\mu k^2 / \varepsilon \\ P = -\langle \underline{u}' \otimes \underline{u}' \rangle : \nabla \underline{u} = v_\varepsilon \underline{d} : \nabla \langle \underline{u}' \rangle \\ \frac{Dk}{Dt} = P + \text{div} \left(\frac{v_\varepsilon}{\sigma_k} \underline{\text{grad}} k \right) - \varepsilon \\ \frac{D\varepsilon}{Dt} = C_{\varepsilon 1} \frac{\varepsilon}{k} P + \text{div} \left(\frac{v_\varepsilon}{\sigma_\varepsilon} \underline{\text{grad}} \varepsilon \right) - C_{\varepsilon 2} \frac{\varepsilon}{k} \varepsilon \end{array} \right.$

\Rightarrow 5 constants : $C_\eta, C_{\varepsilon 1}, C_{\varepsilon 2}, \sigma_k, \sigma_\varepsilon$

17.7 two - equation models : the $k - \varepsilon$ model (...)

- basic flows are used to fix the constants

- flow 1 : temporal decay of isotropic turbulence

$$\Rightarrow \begin{cases} \text{no mean flow : } \nabla \langle \underline{u} \rangle = P = 0 \\ \text{homogeneous turbulence : } \underline{\text{grad}} k = \underline{\text{grad}} \varepsilon = 0 \end{cases}$$

$$\Rightarrow \begin{cases} \frac{dk}{dt} = -\varepsilon \\ \frac{d\varepsilon}{dt} = -C_{\varepsilon 2} \frac{\varepsilon^2}{k} \end{cases} \Rightarrow \boxed{\frac{k(t)}{k(0)} \sim \left(\frac{t}{t_0}\right)^{-\alpha}} \quad \alpha = \frac{1}{C_{\varepsilon 2} - 1} \quad (\text{see training lecture})$$

✓ experiments $\alpha \approx 1.3 \Rightarrow C_{\varepsilon 2} = 1.77$

✓ standart $k - \varepsilon$ model $\alpha \approx 1.09 \Leftarrow \boxed{C_{\varepsilon 2} = 1.92}$

17.7 two - equation models : the $k - \varepsilon$ model (...)

- flow 2 : homogeneous shear flow $\frac{\partial \langle u_i \rangle}{\partial x_j} = S \delta_{i1} \delta_{j2}$

$$\Rightarrow \text{homogeneous turbulence : } \underline{\text{grad}} k = \underline{\text{grad}} \varepsilon = 0 \Rightarrow \begin{cases} P = -S(t) \langle u'_1 u'_2 \rangle \\ \frac{dk}{dt} = P - \varepsilon \end{cases} \quad (1)$$

✓ introducing the time scale $\tau = \frac{k}{\varepsilon}$

$$\frac{d\varepsilon}{dt} = C_{\varepsilon 1} \frac{\varepsilon}{k} P - C_{\varepsilon 2} \frac{\varepsilon^2}{k} \quad (2)$$

(1) \Rightarrow (1') $\boxed{\frac{\tau}{k} \frac{dk}{dt} = \frac{P}{\varepsilon} - 1}$ homework

(1) + (2) \Rightarrow (2') $\boxed{\frac{d\tau}{dt} = (C_{\varepsilon 2} - 1) - (C_{\varepsilon 1} - 1) \frac{P}{\varepsilon}}$ homework

✓ experiments and DNS show that: $\boxed{S \tau \approx \text{const.}}$ $\boxed{\frac{P}{\varepsilon} \approx \text{const.} \approx 1.7}$

(1') $\Rightarrow \frac{k(t)}{k(0)} = e^{t \left(\frac{P}{\varepsilon} - 1 \right)} \rightarrow \infty$ interpretation : turbulence extracts energy in the reservoir of the mean flow energy which is infinite if the flow is statistically homogeneous (no feedback on the mean flow, see §13.6)

(2') $\Rightarrow \frac{C_{\varepsilon 2} - 1}{C_{\varepsilon 1} - 1} = \frac{P}{\varepsilon} \approx 1,7 \quad C_{\varepsilon 2} = 1.77 \Rightarrow \boxed{C_{\varepsilon 1} = 1.45}$

17.7 two - equation models : the $k - \epsilon$ model (...)

✓ **other flows** : boundary layers (log region), jet, ...

⇒ provide the turbulent Prandtl numbers constants $\sigma_k, \sigma_\epsilon$

⇒ suggest other compromises concerning the values of the constants obtained in «pure » situations (isotropy, homogeneity...)

⇒ **standard values**

$$(C_\eta, C_{\epsilon 1}, C_{\epsilon 2}, \sigma_k, \sigma_\epsilon) = (0.09, 1.44, 1.92, 1.0, 1.3)$$

Note - with such values of $C_{\epsilon 1}, C_{\epsilon 2}$ one gets $\frac{P}{\epsilon} = \frac{C_{\epsilon 2} - 1}{C_{\epsilon 1} - 1} \approx 2,1$, instead of $\frac{P}{\epsilon} = 1.7$ as found in homogenous shear flows

⇒ other ajustements are possible from case to case

⇒ no turbulence model can pretend to be universal

17.8 the case of a scalar quantity

• temperature

✓ equation of temperature for a heated flow of newtonian incompressible homogeneous fluid

$$\begin{cases} \rho c \frac{dT}{dt} = 2\eta \underline{\underline{d}} : \underline{\underline{d}} + K \Delta T \\ \epsilon = 2\eta \underline{\underline{d}} : \underline{\underline{d}} \text{ - dissipation rate} \\ c \text{ - heat capacity, } K \text{ - conductivity} \end{cases}$$

✓ neglecting dissipation (see annex)

$$\begin{cases} \frac{dT}{dt} = \chi \Delta T \\ \chi = \frac{K}{\rho c} \text{ = temperature diffusivity} \end{cases}$$

⇒ a « heat equation » valid for describing the **diffusion of any passive scalar** $\theta(\underline{x}, t)$ (temperature ,mass, ...) in a flow

$$\begin{cases} \frac{d\theta}{dt} = \chi \Delta \theta \\ \chi = \text{diffusivity} \end{cases}$$

annex – neglecting dissipation in the heat equation

$$\left\{ \begin{array}{l} \rho c \frac{dT}{dt} = 2\eta \underline{\underline{d}} : \underline{\underline{d}} + K \Delta T \\ \epsilon = 2\eta \underline{\underline{d}} : \underline{\underline{d}} \text{ - dissipation rate} \\ c \text{ - heat capacity, } K \text{ - conductivity} \end{array} \right. \left\{ \begin{array}{l} \text{newtonian incompressible} \\ \text{homogeneous fluid} \end{array} \right.$$

• orders of magnitude

$$x = L \bar{x}, t = \frac{L}{U} \bar{t}, \underline{u} = U \underline{u}, T = T_0 + \delta T \bar{T} \quad \Leftrightarrow \quad \left(\frac{\rho c \delta T U}{L} \right) \frac{d\bar{T}}{d\bar{t}} = \left(\frac{2\eta U^2}{L^2} \right) \underline{\underline{d}} : \underline{\underline{d}} + \left(\frac{K \delta T}{L^2} \right) \Delta \bar{T}$$

$$\Leftrightarrow \frac{d\bar{T}}{d\bar{t}} = 2 \left(\frac{Ec}{Re} \right) \underline{\underline{d}} : \underline{\underline{d}} + \left(\frac{1}{Pr Re} \right) \Delta \bar{T} \quad \left\{ \begin{array}{l} Re = UL/\nu \text{ - Reynolds} \\ Ec = U^2/c\delta T \text{ - Eckert} \\ Pr = \nu/(K/\rho c) \text{ - Prandtl} \end{array} \right.$$

\Leftrightarrow dissipation term negligible if : $\delta T \gg U^2/c$

\Leftrightarrow meaning : small velocity U and temperature variations δT sufficiently large (*)

(*) however, δT must remain in the limit of incompressibility, $\alpha \delta T \ll 1$, where α denotes the dilatation coefficient ($\alpha = 1/T$ for a perfect gaz)

17.8 the case of a scalar quantity (...)

• diffusion equation

$$\left\{ \begin{array}{l} \frac{d\theta}{dt} = \chi \Delta \theta \\ \chi = \text{coefficient of diffusion} \end{array} \right.$$

✓ the transport equation of the mean scalar $\langle \theta \rangle$ reads

$$\frac{D\langle \theta \rangle}{Dt} = \text{div} \left(\chi \underline{\underline{grad}} \langle \theta \rangle - \langle \underline{u}' \theta' \rangle \right)$$

↑
turbulent flux of θ

• Boussinesq's « eddy diffusivity » relationship

$$\langle \underline{u}' \theta' \rangle = - \chi_\epsilon \underline{\underline{grad}} \langle \theta \rangle$$

↑
turbulent diffusivity

$$\Leftrightarrow \rho c \frac{D\langle \theta \rangle}{Dt} = \text{div} \left[\left(\chi + \chi_\epsilon \right) \underline{\underline{grad}} \langle \theta \rangle \right]$$

17.9 conclusion

- **closing the Reynolds equations**

- ✓ a forty years' effort
- ✓ no universal model
- ✓ a choice of models and recommendations

- **« eddy viscosity » models**

- ✓ 95% of the industrial softwares
- ✓ limits: flows strongly out of equilibrium (in strong spectral imbalance)
- ✓ consecutive to rapid mean flow distortions (curvatures, rotations, waves, separations, impacts...)

chapter 18

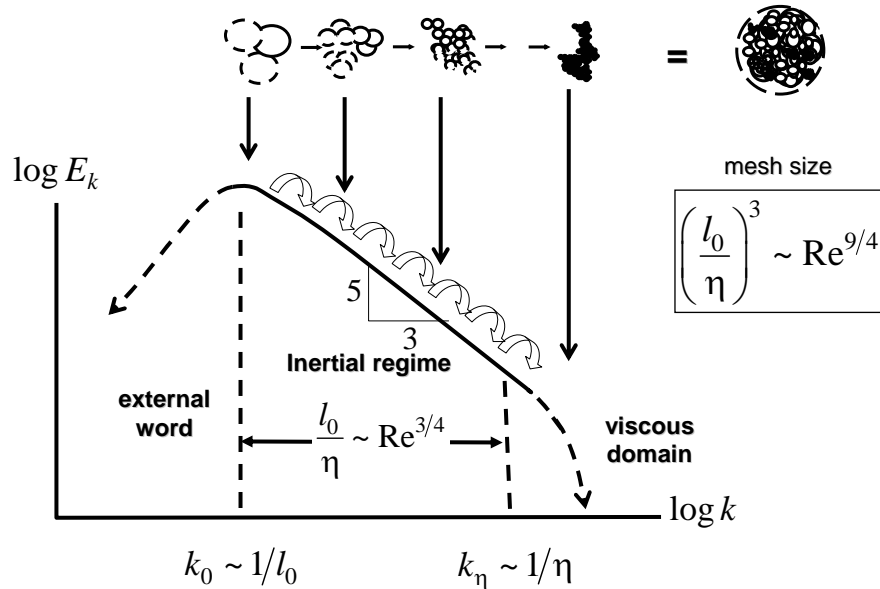
simulations : DNS and LES

18.1 Direct Numerical Simulation (DNS)

18.2 Large Eddy Simulation (LES)

18.1 Direct Numerical Simulation (DNS)

- back to chapter 5



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18.1 Direct Numerical Simulation (DNS) (...)

- the cost of a DNS

✓ spatial mesh size :
$$N_p = \left(\frac{l_0}{\eta}\right)^3 \sim \text{Re}_0^{9/4}$$

✓ time mesh size : $\tau_l \sim \frac{l}{u_l} \sim \frac{l}{(\varepsilon_0 l)^{1/3}} \Rightarrow N_\tau \sim \frac{\tau_0}{\tau_\eta} \sim \frac{(l_0^2/\varepsilon_0)^{1/3}}{(\eta^2/\varepsilon_0)^{1/3}} = \left(\frac{l_0}{\eta}\right)^2 = (\text{Re}_0^{3/4})^2 = \text{Re}_0^{1/2}$

✓ total cost:
$$N_p \times N_\tau \sim \text{Re}_0^{11/4}$$

$$\text{Re}_0 = 10^6 \left\{ \begin{array}{l} N_p \sim 10^{54/4} \approx 310^{13} \\ N_\tau \sim 10^3 \\ N \sim 310^{16} \end{array} \right.$$

- **warning** : precise (high orders) numerical schemes are required.

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18.1 Direct Numerical Simulation (DNS) (...)

- **DNS : state of the art**

- ✓ homogeneous turbulence
 - ✓ unseparated boundary layers
 - ✓ channel, pipes
 - ✓ mixing layers, jets, wakes, trailing vortices
- } at moderate Reynolds number

- **why do we need DNS ?**

- ✓ a DNS is it is the most complete experience that we can achieve. It provides information inaccessible to measurement
- ✓ a successful DNS always becomes a standard reference for physical interpretation and modelling

- **perspectives**

- ✓ an airplane ... in 2070
- ✓ shall we close the wind tunnels in the next century ?

18.2 Large Eddy Simulation (LES)

- **spatial filtering**

$$\overline{u_i}(\underline{x}, t) = G_\Delta * u_i(\underline{x}, t) = \int G_\Delta(\underline{x}, \tilde{\underline{x}}) u_i(\underline{x} - \tilde{\underline{x}}, t) d\tilde{\underline{x}} \quad \int G_\Delta(\underline{x}, \tilde{\underline{x}}) d\tilde{\underline{x}} = 1$$

↑
convolution

(log-log)

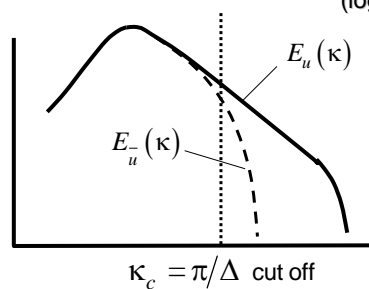
- **properties**

- ✓ decomposition : $u_i = \overline{u_i} + u_i'$
- ✓ non idempotent : $\overline{u_i} = \overline{(\overline{u_i} + u_i')} = \overline{\overline{u_i}} + \underbrace{\overline{u_i'}}_{\neq 0}$
 $\Rightarrow \overline{\overline{u_i}} \neq \overline{u_i}$
- ✓ commutation with time derivation

- ✓ commutation with space derivation at the condition where :

$$G_\Delta(\underline{x}, \tilde{\underline{x}}) = G_\Delta(\underline{x} - \tilde{\underline{x}})$$

homogeneous filter
(see annex)



annex – LES : space filtering and derivation

✓ space derivation of the convolution product $\bar{u}_i(\underline{x}, t) = \int G_\Delta(\underline{x}, \tilde{\underline{x}}) u_i(\underline{x} - \tilde{\underline{x}}, t) d\tilde{\underline{x}}$

$$\begin{aligned} \frac{\partial \bar{u}_i(\underline{x}, t)}{\partial x_j} &= \int G_\Delta(\underline{x}, \tilde{\underline{x}}) \frac{\partial u_i(\underline{x} - \tilde{\underline{x}}, t)}{\partial x_j} d\tilde{\underline{x}} + \int \frac{\partial G_\Delta(\underline{x}, \tilde{\underline{x}})}{\partial x_j} u_i(\underline{x} - \tilde{\underline{x}}, t) d\tilde{\underline{x}} + \\ &= \overline{\left(\frac{\partial u_i}{\partial x_j} \right)}(\underline{x}, t) + \int \frac{\partial G_\Delta(\underline{x}, \tilde{\underline{x}})}{\partial x_j} u_i(\underline{x} - \tilde{\underline{x}}, t) d\tilde{\underline{x}} \end{aligned}$$

$$\frac{\partial \bar{u}_i(\underline{x}, t)}{\partial x_j} = \overline{\left(\frac{\partial u_i}{\partial x_j} \right)}(\underline{x}, t) \quad \Leftrightarrow \quad \boxed{G_\Delta(\underline{x}, \tilde{\underline{x}}) = G_\Delta(\underline{l} = \underline{x} - \tilde{\underline{x}})}$$

homogeneous filter

18.2 Large Eddy Simulation (LES) (...)

• filters : examples

✓ « box filter »

$$G_\Delta(\underline{x} - \tilde{\underline{x}}) = \begin{cases} 1/\Delta^3 & \text{if } \|\underline{x}_i - \tilde{\underline{x}}_i\| \leq \frac{\Delta}{2} \\ 0 & \text{otherwise} \end{cases}$$

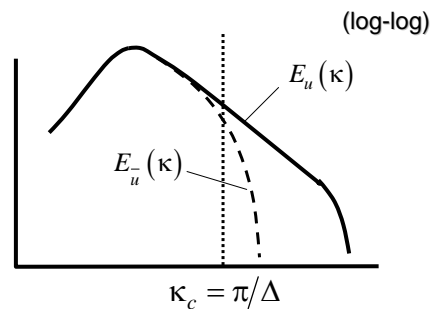
$$\Delta = (\Delta x_1 \Delta x_2 \Delta x_3)^{1/3}$$

✓ gaussian filter

$$G_\Delta(\underline{x} - \tilde{\underline{x}}) = \left(\frac{6}{\pi}\right)^{3/2} \frac{1}{\Delta^3} \exp\left(-6 \frac{(\underline{x} - \tilde{\underline{x}})^2}{\Delta^2}\right)$$

✓ spectral filter

$$G_\Delta(\underline{\kappa}) = \begin{cases} 1 & \text{if } \|\underline{\kappa}\| \leq \kappa_c = \frac{\pi}{\Delta} \\ 0 & \text{otherwise} \end{cases}$$



• resolution

✓ L = size of the computational domain

✓ N_p points in each directions

⇒ mesh size : $h = \frac{L}{N_p}$

⇒ maximum resolution : $\kappa_{\max} = \frac{2\pi}{h}$

⇒ $\kappa_c \leq \frac{\kappa_{\max}}{2} = \frac{\pi}{h}$ (Nyquist theorem)

18.2 Large Eddy Simulation (LES) (...)

• space filtered Navier- Stokes equations

✓ same as the Reynolds decomposition : $\underline{u}(\underline{x}, t) = \overline{\underline{u}}(\underline{x}, t) + \underline{u}'(\underline{x}, t)$

✓ however now : $\begin{cases} \overline{\underline{u}} \neq \underline{u} \\ \underline{u}' \neq 0 \end{cases}$

✓ continuity $\begin{cases} \text{div } \overline{\underline{u}} = 0 = \text{div } \underline{u} \\ \text{div } \underline{u}' = \text{div}(\underline{u} - \overline{\underline{u}}) = 0 \end{cases}$ **nota** : only homogeneous filters are considered

✓ momentum $\frac{D\overline{\underline{u}}}{Dt} = \frac{\partial \overline{\underline{u}}}{\partial t} + \text{div}(\overline{\underline{u}} \otimes \overline{\underline{u}}) = -\frac{1}{\rho} \text{grad } \overline{p} + \text{div}(\nu \nabla \overline{\underline{u}} - \underline{\underline{\tau}}^L)$

• Leonard's tensor

$$\underline{\underline{\tau}}^L = \underbrace{\left[(\overline{\underline{u}} \otimes \overline{\underline{u}} - \overline{\underline{u} \otimes \underline{u}}) + \overline{\underline{u}} \otimes \underline{u}' + \underline{u}' \otimes \overline{\underline{u}} \right]}_{\text{additional terms}} + \underbrace{\overline{\underline{u}' \otimes \underline{u}'}}_{\langle \underline{u}' \otimes \underline{u}' \rangle \text{ Reynolds stress tensor}}$$

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18.2 Large Eddy Simulation (LES) (...)

• Leonard's tensor (...)

$$\underline{\underline{\tau}}^L = \underbrace{\left[(\overline{\underline{u}} \otimes \overline{\underline{u}} - \overline{\underline{u} \otimes \underline{u}}) \right]}_{\text{resolved scales}} + \underbrace{\left[\overline{\underline{u}} \otimes \underline{u}' + \underline{u}' \otimes \overline{\underline{u}} \right]}_{\text{strain due to scale interactions } \kappa < \kappa_c \text{ and } \kappa > \kappa_c} + \underbrace{\overline{\underline{u}' \otimes \underline{u}'}}_{\text{« subgrid scale » strain } \kappa > \kappa_c}$$

• filtered kinetic energy

$$\overline{e_c} = \underbrace{\frac{1}{2} \overline{\underline{u}} \cdot \overline{\underline{u}}}_{\text{resolved scale energy } = K_c} + \underbrace{\frac{1}{2} (\overline{\underline{u} \cdot \underline{u}} - \overline{\underline{u}} \cdot \overline{\underline{u}})}_{k_c = \text{residual energy}}$$

$P_c = \tau_{il}^R \frac{\partial \overline{u}_i}{\partial x_l}$
exchanges

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annex – LES : equation of the filtered kinertic energy

✓ the $K_c = \frac{1}{2} \overline{u_i u_i}$ - equation comes from the multiplication of the $\overline{u_i}$ - equation by $\overline{u_i}$

$$\overline{u_i} \times \left(\frac{\partial \overline{u_i}}{\partial t} + \overline{u_l} \frac{\partial \overline{u_i}}{\partial x_l} - \frac{1}{\rho} \frac{\partial \overline{p}}{\partial x_l} + \frac{\partial}{\partial x_l} \left(\nu \frac{\partial \overline{u_i}}{\partial x_l} - \tau_{il}^R \right) \right)$$

✓ this gives an equation analogous for that obtained using Reynolds averaging

$$\frac{\overline{D} K_c}{\overline{D} t} = \underbrace{\frac{\partial K_c}{\partial t} + \overline{u_l} \frac{\partial K_c}{\partial x_l}}_{C = \text{convection}} = \underbrace{-\tau_{il}^R \frac{\partial \overline{u_i}}{\partial x_l}}_{P = \text{échange avec } k_c} + \underbrace{\frac{\partial}{\partial x_l} \left(-\frac{\overline{p u_i}}{\rho} + \nu \frac{\partial \overline{u_i}}{\partial x_l} - \overline{u_i} \tau_{il}^R \right)}_{D = \text{diffusion}} - \underbrace{\nu \left(\frac{\partial \overline{u_i}}{\partial x_l} \right)^2}_{\varepsilon_{K_c} = \text{dissipation}}$$

18.2 Large Eddy Simulation (LES) (...)

• closure : the eddy viscosity concept

✓ space filtering

$$\frac{\overline{D} \underline{\underline{u}}}{\overline{D} t} = \text{div} \left(\underline{\underline{\sigma}} - \underline{\underline{\tau}}^R \right)$$

$$\left\{ \begin{array}{l} \underline{\underline{\sigma}} = -\frac{1}{\rho} \overline{p} \underline{\underline{1}} + \nu \underline{\underline{d}} \\ \underline{\underline{\tau}}^R - \text{Leonard's tensor} \end{array} \right.$$

✓ ensemble average

$$\frac{D \langle \underline{\underline{u}} \rangle}{Dt} = \text{div} \left(\langle \underline{\underline{\sigma}} \rangle - \underline{\underline{R}} \right)$$

$$\left\{ \begin{array}{l} \langle \underline{\underline{\sigma}} \rangle = -\frac{1}{\rho} \langle p \rangle \underline{\underline{1}} + \nu \langle \underline{\underline{d}} \rangle \\ \underline{\underline{\tau}}^R - \text{Reynolds' tensor} \end{array} \right.$$

• analogy

$$\underline{\underline{\tau}}^R = \frac{1}{3} \text{Tr} \left\{ \underline{\underline{\tau}}^R \right\} \underline{\underline{1}} = -2 \nu_T \underline{\underline{d}}$$

Smagorinsky model (*)

• there are many other possibilities

(*) 1963, researcher in meteorology which has developed firstly LES

18.2 Large Eddy Simulation (LES) (...)

• space filtering versus ensemble average

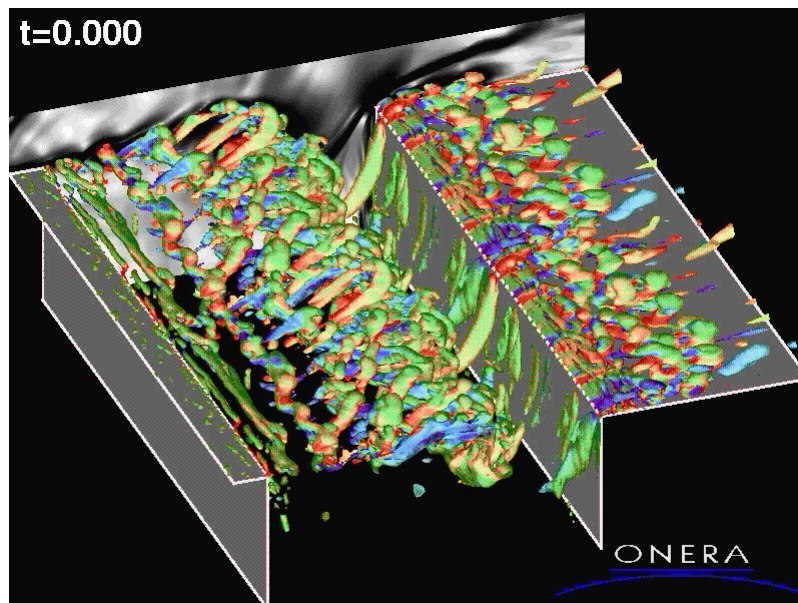
✓ moyenne d'ensemble : $\langle \underline{u} \rangle(\underline{x}), \langle p \rangle(\underline{x}), \underline{R}(\underline{x})$

- deterministic
(if statistically steady)

✓ filtrage spatial : $\bar{\underline{u}}(\underline{x}, t), \bar{p}(\underline{x}, t), \underline{\tau}^R(\underline{x}, t)$

- random
- depend on the filter parameters

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Larchevêque et al. (2002)

18.2 Large Eddy Simulation (LES) (...)

- **LES : state of the art**

- ✓ same as DNS but at higher Reynolds
- ✓ flow around 2D objects (e.g. wing profiles)
- ✓ an efficient method for computing free turbulent shear flows (jets...)
- ✓ for wall flows one still needs to solve $y^+ = 1$
- ✓ difficult to discriminate between the respective influences of the model, the mesh size (the cutt off) and the numerics

- **perpectives**

- ✓ unclear (« bad » DNS...)
- ✓ supplanted by other cheaper methods, such as the DES which mixes the Reynodls approach in wall regions and LES in free flow regions

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18.3 conclusions

- **numerical simulations**

- ✓ far to be operational for applications
- ✓ future depends on computer science
- ✓ meanwhile, we must keep on modelizing ... and we must keep on doing experiments

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