

1- Interaction of two counter rotating vortices : The Crow instability (solution)

(a) Position-velocity

$$\begin{cases} \frac{d\bar{Z}_1}{dt} = \frac{\Gamma_2}{2\pi i(Z_1 - Z_2)} = \frac{\Gamma}{2\pi i(Z_1 - Z_2)} \\ \frac{d\bar{Z}_2}{dt} = \frac{\Gamma_1}{2\pi i(Z_2 - Z_1)} = \frac{-\Gamma}{2\pi i(Z_2 - Z_1)} \end{cases} \Rightarrow \boxed{\bar{Z}_2 - \bar{Z}_1 = \underbrace{(y_2 - y_1)}_{=b} - i \underbrace{(z_2 - z_1)}_{=0} = Cte}$$

$$\frac{d\bar{Z}_j}{dt} = v_j - iw_j = \frac{-\Gamma}{2\pi ib} \Rightarrow \boxed{v_1 = v_2 = 0, w_1 = w_2 = -\frac{\Gamma}{2\pi b}}$$

The vortices are advected downward, and the distance between them remains constant.

(b) At $Z_0 = Z_j + \tilde{Z}_j$, the velocity induced by the other vortex (Γ_k, Z_k) is :

$$\frac{d\bar{Z}_0}{dt} = \frac{d\bar{Z}_j}{dt} + \frac{d\tilde{Z}_j}{dt} = \frac{\Gamma_k}{2\pi i(Z_0 - Z_k)}, \text{ with } \frac{d\tilde{Z}_j}{dt} = \frac{\Gamma_k}{2\pi ib} \text{ and } Z_0 - Z_k = \pm b + \tilde{Z}_j$$

Hence :
$$\frac{d\tilde{Z}_j}{dt} = \frac{\Gamma_k}{2\pi i} \left(\frac{1}{\tilde{Z}_j \pm b} - \frac{1}{\pm b} \right) = \frac{\Gamma_k}{2\pi i(\pm b)} \left(\frac{1}{1 + \tilde{Z}_j/(\pm b)} - 1 \right) = \frac{\Gamma_k}{2\pi i(\pm b)} \left(-\tilde{Z}_j/(\pm b) + O\left(\left(\frac{\tilde{Z}_j}{b}\right)^2\right) \right)$$

$$\frac{d\tilde{Z}_j}{dt} = i \frac{\Gamma_k}{2\pi b^2} \tilde{Z}_j. \text{ So } \boxed{\frac{d\tilde{Z}_j}{dt} = i\lambda_k \tilde{Z}_j}$$

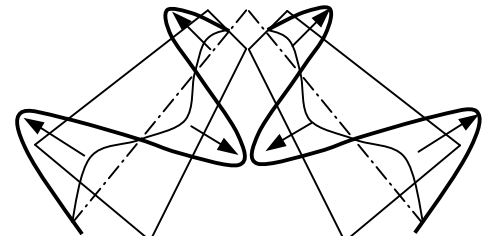
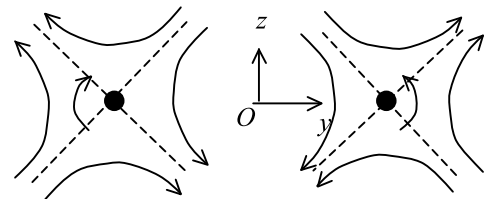
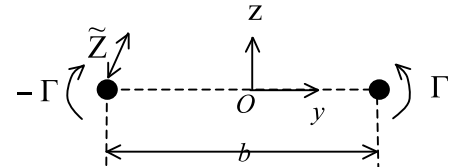
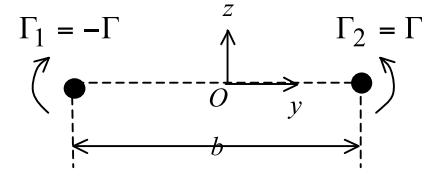
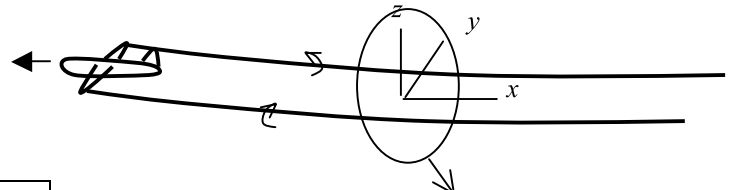
(c) Solutions
$$\frac{d^2 \tilde{Z}_j}{dt^2} = i\lambda_k \frac{d\tilde{Z}_j}{dt} = (i\lambda_k \chi - i\lambda_k) \tilde{Z}_j = \lambda_k^2 \tilde{Z}_j \Rightarrow \boxed{\tilde{Z}_j(t) \propto \tilde{Z}_j(0) e^{\pm\lambda_k t}}$$

Streamlines. Streamlines are defined by $\frac{dy}{v} = \frac{dz}{w} = Cstt$.

$$\frac{d\tilde{Z}_j}{dt} = \frac{d}{dt} (\tilde{y}_j - i\tilde{z}_j) = i\lambda_k (\tilde{y}_j + i\tilde{z}_j) \Rightarrow \begin{cases} \frac{d\tilde{y}_j}{dt} = -\lambda_k \frac{\tilde{z}_j}{b} \\ \frac{d\tilde{z}_j}{dt} = -\lambda_k \frac{\tilde{y}_j}{b} \end{cases}$$

Hence
$$\frac{d\tilde{y}_j}{\lambda_k \tilde{z}_j} = \frac{d\tilde{z}_j}{\lambda_k \tilde{y}_j} = Cstt \Rightarrow \boxed{\tilde{y}_j^2 - \tilde{z}_j^2 = Cstt}$$

This is a shear oriented at 45°.



(d) A sinusoidal deformation in the plane of the shear is amplified. We obtain the picture above: The contact between the two vortices creates a cut (zero total vorticity at those points), which transforms the flow into a series of vortex rings.

If the perturbation is not in the plane of the shear, one can show that each vortex rotates around its axis (self-rotation), which eventually triggers the instability described above (alignment in the plane of the shear and amplification). This instability, known as the Crow instability (Crow, *Journal of Aircraft*, 1970) can sometimes be observed behind planes.

2- Vortex stretching : tornado (Burgers vortex) : solution

Hypothesis : $\frac{\partial u}{\partial \theta} = 0, \underline{\omega} = \omega_z \underline{e}_z$.

(a) **Vorticity :** $\omega_z(r, z, t) = \frac{1}{r} \frac{\partial r u_\theta}{\partial r}$. $div(\underline{\omega}) = \frac{\partial \omega_z}{\partial z} = 0 \Rightarrow \omega_z = \omega_z(r, t) \Rightarrow u_\theta = u_\theta(r, t)$; $\omega_r = -\frac{1}{r} \frac{\partial u_\theta}{\partial z} = 0 \Rightarrow$ same ; $\omega_\theta = \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} = 0 \Rightarrow$

$$\frac{\partial u_r}{\partial z} = \frac{\partial u_z}{\partial r}$$

vorticity equation :
$$\underbrace{\begin{vmatrix} 0 \\ 0 \\ \frac{\partial \omega_z}{\partial t} \end{vmatrix}}_{\frac{\partial \underline{\omega}}{\partial t}} + \underbrace{\begin{vmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \frac{\partial \omega_z}{\partial r} & 0 & 0 \end{vmatrix}}_{\underline{grad} \omega_z} + \underbrace{\begin{vmatrix} \frac{\partial u_r}{\partial r} & -u_\theta/r & \frac{\partial u_r}{\partial z} \\ \frac{\partial u_\theta}{\partial r} & u_r/r & 0 \\ \frac{\partial u_z}{\partial r} & 0 & \frac{\partial u_z}{\partial z} \end{vmatrix}}_{\underline{grad} u \cdot \underline{\omega}} \begin{vmatrix} u_r \\ u_\theta \\ \omega_z \end{vmatrix} + \nu \Delta \omega_z$$
. The first equation leads to $0 = \omega_z \frac{\partial u_r}{\partial z} \Rightarrow u_r = u_r(r, t)$.

From $\omega_\theta = \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} = 0, \frac{\partial u_z}{\partial r} = 0 \Rightarrow u_z = u_z(z, t)$. The last one is :

$$\frac{\partial \omega_z}{\partial t} + \underbrace{u_r \frac{\partial \omega_z}{\partial r}}_{\text{Advection}} = \underbrace{\omega_z \frac{\partial u_z}{\partial z}}_{\text{Stretching}} + \underbrace{\nu \Delta \omega_z}_{\text{Diffusion}}$$

(b) Velocity

- Continuity : $\frac{1}{r} \frac{\partial r u_r}{\partial r} + \frac{\partial u_z}{\partial z} = 0 \Rightarrow \frac{\partial}{\partial z} \left(\frac{1}{r} \frac{\partial r u_r}{\partial r} + \frac{\partial u_z}{\partial z} \right) = \frac{\partial^2 u_z}{\partial z^2} = 0 \Rightarrow u_z(z, t) = S(t) z$
 $\Rightarrow \frac{1}{r} \frac{\partial r u_r}{\partial r} = -S(t) \Rightarrow u_r(r, t) = -\frac{S(t)}{2} r^2$

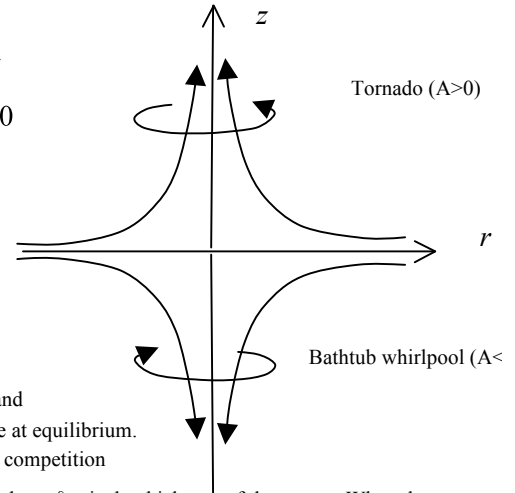
Note that the last equation assumes that there is no source at $r = 0$.

(c) Streamlines : $\frac{dr}{u_r} = \frac{dz}{u_z} \Rightarrow -\frac{2}{S(t)} \frac{dr}{r} = \frac{1}{S(t)} \frac{dz}{z} \Rightarrow d \ln(r^{-2}) = d \ln z \Rightarrow z = A r^{-2}$ see below.

(d) The vorticity equation is therefore :

Case $S(t) > 0$

$$\frac{\partial \omega_z}{\partial t} + \underbrace{-\frac{S(t)}{2} r \frac{\partial \omega_z}{\partial r}}_{\text{Advection toward the center}} = \underbrace{S(t) \omega_z}_{\text{Amplification by stretching}} + \underbrace{\nu \Delta \omega_z}_{\text{Viscous Spreading}}$$



The vorticity is advected toward the center where it is amplified by stretching

(e) At the center $r = 0$, the temporal variation of ω_z results in the competition between the stretching and the diffusion which tends to spread the vortex. A steady state can be reached if those two mechanisms are at equilibrium.

At $r = 0$ there is no advection term in the above equation. The evolution of $\omega(0, t)$ is determined by the competition between stretching, acting on a time scale $\tau_S = S^{-1}$ and diffusion, acting on a time scale, $\tau_\nu = \delta_B^2/\nu$ where δ_B is the thickness of the vortex. When the two opposite effects are at equilibrium, $\delta_B = \sqrt{\nu/S}$, the flow is stationary. This scale resulting from the balance stretching/spreading is the « Burgers scale ».

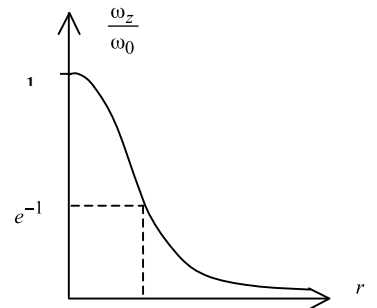
(f) At steady state : $0 = \frac{S}{2} r \frac{d\omega_z}{dr} + S\omega_z + \nu \frac{1}{r} \frac{d}{dr} \left(r \frac{d\omega_z}{dr} \right)$, hence :

$$0 = \frac{S}{2} r \frac{d^2 \omega_z}{dr^2} + \nu \frac{1}{r} \frac{d}{dr} \left(r \frac{d\omega_z}{dr} \right) = \frac{1}{r} \frac{d}{dr} \left(S \frac{r^2}{2} \omega_z + \nu r \frac{d\omega_z}{dr} \right) \Rightarrow \left(S r \frac{\omega_z}{2} + \nu \frac{d\omega_z}{dr} \right) = Cst$$
. Hence :

$$\frac{d \ln \omega_z}{dr} = -\frac{S r}{2\nu} \Rightarrow \omega_z = \omega_0 e^{-\frac{S r^2}{4\nu}} = \omega_0 e^{-\left(\frac{r}{\delta_B}\right)^2}$$

This solution is determined by the characteristic scale (Burgers scale) :

$\delta_B = 2\sqrt{\frac{\nu}{S}}$ which results from the competition between the two mechanisms stretching/diffusion



(g) The circulation is : $\Gamma = 2\pi \int_0^\infty \omega_z r dr = 2\pi \omega_0 \int_0^\infty e^{-\frac{S r^2}{4\nu}} r dr = 2\pi \omega_0 \frac{4\nu}{2S} = \omega_0 \frac{4\pi\nu}{S}$. Hence : $\omega_0 = \frac{1}{4\pi\nu} \Gamma$

$$\delta_B = 2\sqrt{\frac{\nu}{S}}$$